Part C: Linear Algebra and Numerical Methods DOCTORAL QUALIFYING EXAM, MAY 2013

The first three questions are about Linear Algebra and the next three questions are about Numerical Methods.

1. Let $P_{C(A)}$ denote the orthogonal projection operator onto the column space of matrix A. (a) Show that

$$UP_{C(A)} = P_{C(UA)}U$$

for any real $m \times n$ matrix A and unitary $m \times m$ matrix U.

- (b) Show that $P_{C(A)} + P_{C(B)}$ is a projection if and only if $P_{C(A)}P_{C(B)} = 0$.
- 2. Let $V \subset \mathbb{R}^3$ be the subspace spanned by $(4, 1, -2)^T$. Suppose we define an inner product for $x, y \in \mathbb{R}^3$ by

$$(x,y) = 2x_1y_1 + 3x_2y_2 + x_3y_3.$$

(a) Find a basis for $V^{\perp} = \{x | (x, y) = 0 \ \forall y \in V\}.$

(b) Find C and D in the linear fit y(t) = Ct + D that minimizes the weighted squared error $||y(t) - (Ct + D)||^2$, as defined using the norm induced by the above inner product, for data y(-1) = -1, y(0) = 0, y(1) = 0.

3. Consider the system of differential equations given by

$$\frac{dx}{dt} = \begin{pmatrix} 1 & 0 & 0 & 0\\ 1 & 1 & 0 & 0\\ 0 & 0 & -1 & 0\\ 0 & 0 & 1 & -1 \end{pmatrix} x.$$

- (a) Find the fundamental solution X(t) satisfying X(0) = I.
- (b) Show that if $t \ge 0$,

$$||X(t)|| = \left(1 + \frac{1}{2}t^2 + \frac{1}{2}t\sqrt{4+t^2}\right)^{1/2}e^t$$

where ||X|| is the standard matrix (operator) norm

$$||X|| = \max_{x \neq 0} \frac{||Xx||}{||x||}$$

and ||x|| is the Euclidean norm of vector x.

4. Explain how Newton's method can be used to find the solutions to the equation $x^2 = 2$. Write down the approximate solution after two iterations with initial guess $x_0 = 1$. Show that the Newton's iterations converge for any nonzero initial guess. 5. Consider the initial value problem

$$y' = f(t, y), \ y(0) = y_0.$$

One possibility to derive numerical schemes for the initial value problem above is to consider the following family of k-multistep methods of the form

$$\sum_{j=-1}^{k-1} a_j y_{n-j} = h f_{n+1}$$

where the coefficients a_j are determined by (1) constructing the polynomial p_k of degree k that interpolates y_{n-j} at $t_{n-j} = (n-j)h$ for $j = -1, \ldots, k-1$, (2) evaluating $p'_k(t_{n+1}) \approx y(t_{n+1})$, and (3) equating $p'_k(t_{n+1}) = f_{n+1}$.

(a) Show that for k = 1, 2 these methods are given explicitly by

$$y_{n+1} - y_n = h f_{n+1}$$

$$(3y_{n+1} - 4y_n + y_{n-1})/2 = h f_{n+1}$$
(1)

(b) What is the order of these methods for k = 1, 2? How about for a general k?

(c) Show that for k = 1 and 2 the methods are stable, and for k = 1 the method is A-stable. Are the methods convergent in those cases?

6. (a) Consider the inner product

$$\langle f,g\rangle = \int_{-1}^1 (x+1)f(x)g(x)dx$$

and let \mathcal{P}_n be the set of polynomials of degree at most n. Let $Q \in \mathcal{P}_n$ be a nontrivial polynomial which is $\langle \cdot, \cdot \rangle$ -orthogonal to \mathcal{P}_{n-1} . Construct such a polynomials in terms of the Legendre polynomials $\{P_0, P_1, \ldots, P_n, \ldots\}$ which are orthogonal in $L^2(-1, 1]$) and normalized such that $P_n(1) = 1$ for all $n \geq 0$.

(b) Consider the quadrature

$$I_n^1(g) = \sum_{i=1}^n c_i g(x_i) \approx \int_{-1}^1 (x+1)g(x)dx$$

where $\{x_i\}$ is the set of zeros of Q and c_i are chosen so that I_n^1 is exact for \mathcal{P}_{n-1} . Show that I_n^1 is, in fact, exact for \mathcal{P}_{2n-1} .

(c) Show that there exist coefficients $\{a_i\}$ for i = 0, 1, ... which make the formula exact for \mathcal{P}_{2n}

$$I_n(f) = a_0 f(-1) + \sum_{i=1}^n a_i f(x_i) \approx \int_{-1}^1 f(x) dx.$$

Here the nodes x_i are given in Part (b). Show that this quadrature is not exact for \mathcal{P}_{2n+1} . (d) For the Gaussian quadrature rule $\int_{-1}^{1} f(x) dx \approx J_n f = \sum_{i=1}^{n} w_i f(y_i)$, prove that $\lim_{n\to\infty} J_n f = \int_{-1}^{1} f(x) dx$ for all $f \in C([-1, 1])$.