DOCTORAL QUALIFYING EXAM Department of Mathematical Sciences New Jersey Institute of Technology

Applied Math Part C: Linear Algebra and Numerical Methods

The first three questions are about Linear Algebra and the next three questions are about Numerical Methods.

- (a) Let A be a real 3 × 3 symmetric matrix with eigenvalues 0, 3, and 5 and corresponding eigenvectors u, v, and w. (i) Find a basis for the nullspace of A and a basis for the column space of A. (ii) If possible, find the solution(s) of Ax = u. (iii) Is A invertible?
 Solve the problem for the general case. Do not assume a specific matrix.
 - (b) i. Let A and B be similar matrices. Show that they have the same determinant.
 - ii. Let A and B be similar matrices. Show that they have the same characteristic equations and, thus, eigenvalues. Do not use (ii) to prove (i).
- 2. (a) Use the Gauss-Seidel method to find a solution to the linear system $A\mathbf{x} = \mathbf{b}$, where: $A = \begin{pmatrix} 1 & -5 \\ 7 & -1 \end{pmatrix}$ and $\mathbf{b} = \begin{bmatrix} -4 & 6 \end{bmatrix}^T$. Start with the initial condition $\mathbf{x} = \begin{bmatrix} 0 & 0 \end{bmatrix}^T$ and use four iterations. Make sure that the

start with the initial condition $\mathbf{x} = \begin{bmatrix} 0 & 0 \end{bmatrix}$ and use four iterations. Make sure that the method converges to the true solution. Discuss convergence of the Gauss-Seidel method for this case.

- (b) Solve the system with partial pivoting.
- 3. (a) Let: $A = \begin{pmatrix} 1 & 1 & 2 \\ 4 & 1 & 2 \\ -3 & 0 & 0 \end{pmatrix}$. Find an orthonormal basis for the vector space spanned by all vectors **b** for which the system $A\mathbf{x} = \mathbf{b}$ is consistent. When the system is consistent, how many solutions does it have and why?
 - (b) Let A be an $m \times n$ matrix. Prove that A and $A^T A$ have the same nullspace.
- 4. (a) Let x_0, \ldots, x_n be distinct nodes and let f be a given real valued function with n+1 continuous derivatives. Let $P_n(x)$ be the Lagrange polynomial of degree n satisfying $P_n(x_i) = f(x_i)$ for $i = 0, \ldots, n$. Prove that for each x in the domain of f there is a $\xi \in \mathbb{R}$ with

$$f(x) - P_n(x) = \frac{(x - x_0) \dots (x - x_n)}{(n+1)!} f^{(n+1)}(\xi).$$

(b) Prove that the function g(x) = 1/(2+x) has a unique fixed point x_* in [0, 1] and describe the convergence of the iteration $x_{n+1} = g(x_n), x_0 = 1$. 5. Consider initial value problems of the form $y' = f(t, y), y(0) = y_0 \in \mathbb{R}$, where f is infinitely differentiable. Consider the family of explicit methods with uniform step size h given by

$$y_{n+1} = a_0 y_n + a_1 y_{n-1} + h \left[b_0 f(t_n, y_n) + b_1 f(t_{n-1}, y_{n-1}) \right]$$

and suppose that $a_1 = 1 - a_0$.

- (a) For which values of a_0, b_0 and b_1 is the method consistent?
- (b) For which values of a_0, b_0 and b_1 will the method converge?
- 6. Suppose f is infinitely differentiable, and consider the definite integral

$$I(f) = \int_{a}^{b} f(x) dx.$$

Let $T_h(f)$ and $M_h(f)$ denote the composite trapezoidal and composite midpoint rule approximations of I(f) with uniform subintervals of length h.

- (a) Show that $T_{\frac{h}{2}}(f) = \frac{1}{2} (T_h(f) + M_h(f)).$
- (b) As $h \to 0$, the Euler-MacLaurin formula states that there is an asymptotic relation of the form

$$T_h(f) = I(f) + k_2h^2 + k_4h^4 + O(h^6),$$

where the constants k_2, k_4 are independent of h. Find a similar rule for $M_h(f)$.

(c) Apply one step of Richard extrapolation to derive a fourth order accurate quadrature formula using $M_h(f)$ and $M_{2h}(f)$.